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adaptive filter resulting in an output $y(n)$. The input is also sent through a delay to attain $d(n)$. As the error signal is converging to zero, the adaptive filter coefficients $w(n)$ are converging to the inverse of the unknown system $u(n)$. For this configuration, as for the system identification configuration, the error can theoretically go to zero.

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Subband Adaptive Filtering Theory and Implementation Kong-Aik Lee Institute for Infocomm Research, Singapore Woon-Seng Gan Nanyang Technological University, Singapore Sen M. Kuo Northern Illinois University, USA A John Wiley and Sons, Ltd., Publication. This edition first published 2009

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adaptive weights with superscript T denoting transpose, and. $e(t) = d(t) - w'y(t)$ is the filtered reference signal vector, where $c(t)$ is the impulse response of the cancellation path, * denotes convolution, and $z(t) = [z(t - N + 1) \dots z(t - 1)]^T$ is a vector comprising the N most recent reference samples.

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An adaptive filter is a system with a linear filter that has a transfer function controlled by variable parameters and a means to adjust those parameters according to an optimization algorithm. Because of the complexity of the optimization algorithms, almost all adaptive filters are digital filters.

Adaptive filter - Wikipedia

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